

Abstract of the Disclosure

A radar, sonar, lidar or like active detection, tracking system calculates the clutter which would occur with various different transmit waveforms, and selects from among those waveforms that one which, given the current clutter, is expected to minimize variation or variability of the clutter. The calculation is performed by generating a clutter kernel for the current transmitted or other reference waveform, and calculating the clutter which would result with alternate transmit waveform(s). The variability of the various clutter responses is determined, and the transmit waveform exhibiting the least clutter variability is selected for a later transmission.